



UAV



VEHICLE



BACKPACK

QUICK SPECS

Absolute Accuracy

2-3.5 cm RMSEz @ 75 m ^{(1) (3)}

Intrawath Precision

3 cm RMSDz @ 75 m ^{(1) (2)}

PP Attitude Heading RMS Error

0.019°

Weight

2.2 kg / 4.9 lbs.

(2.5 kg with A6K-Lite)

Dimensions

Without A6K-Lite:

240 x 130 x 180 mm

With A6K-Lite:

300 x 130 x 180 mm

Laser Range

250 m @ 60% Reflectivity

Scan Rate

100 k shots/s, up to 5 returns

miniRANGER-LITE

The **miniRANGER-LITE** is a system that features an impressive recommended AGL of up to 75 meters, filling a major AGL gap in the ultra-lightweight UAV LiDAR market. With the photogrammetry package, operators of mid-size multirotors, like the DJI M600 Pro, can now simultaneously acquire survey-grade LiDAR data and high resolution 24 MP (up to 61 MP if required) RTK photogrammetry at up to 100 m operating flight altitude.

FEATURES

- » Includes the new weight optimized Air NavBox for increased range & flexibility
- » Flexible mounting to drones such as DJI M600 and M300 with our custom vibration isolator mounts
- » High resolution 61 MP camera option available

PLATFORM

| | |
|-----------------------------|---|
| OVERALL DIMENSIONS (SENSOR) | Without A6K-Lite: 240 x 130 x 180 mm With A6K-Lite: 300 x 130 x 180 mm |
| OPERATING VOLTAGE | 12 - 28V DC |
| POWER CONSUMPTION | Without A6K-Lite: 30W (typical) With A6K-Lite: 38W (typical) |
| OPERATING TEMPERATURE | -10° - +40° C |
| WEIGHT WITH A6K-LITE CAMERA | 2.5 kg |

LiDAR SENSOR

| | |
|-----------------------------------|---------------------------|
| LASER PROPERTIES | 905 nm Class 1 (eye safe) |
| RANGE MIN | 3 m |
| MAX EFFECTIVE MEASUREMENT RATE | 100,000 meas./sec |
| HORIZONTAL FIELD OF VIEW | 360° |
| ACCURACY | 15mm one Sigma @ 50 m |
| MAX MEASURING RANGE ρ 20% (ρ 60%) | 150 m (250 m) |
| SENSOR CLASSIFICATION | IP64 |
| WEIGHT | 1.55 kg |
| POWER CONSUMPTION | 18 W (typical) |

NAVIGATION SYSTEM

| | |
|-------------------------------|------------------------------------|
| CONSTELLATION SUPPORT | GPS + GLONASS + BEIDOU + GALILEO |
| SUPPORT ALIGNMENT | Kinematic, Single-Antenna |
| OPERATION MODES | Real-time, Postprocessing optional |
| ACCURACY POSITION | 1 cm + 1 ppm RMS horizontal |
| PP ATTITUDE HEADING RMS ERROR | 0.019° |



Oil & Gas Surveying



Utilities Mapping



Railway Track Mapping



Agriculture & Forestry Monitoring



Construction Site Surveying



Open Pit Mining Operations



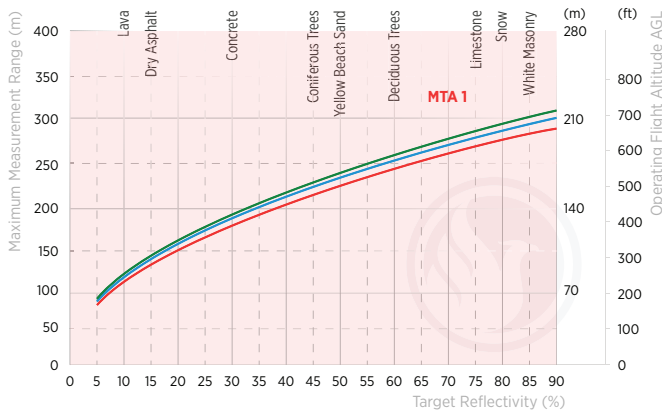
General Mapping

¹⁾ Approximate values based on PLS test conditions using a 90° downward field of view

²⁾ Range of elevation values on flat surface with >20% reflectivity at the laser's wavelength

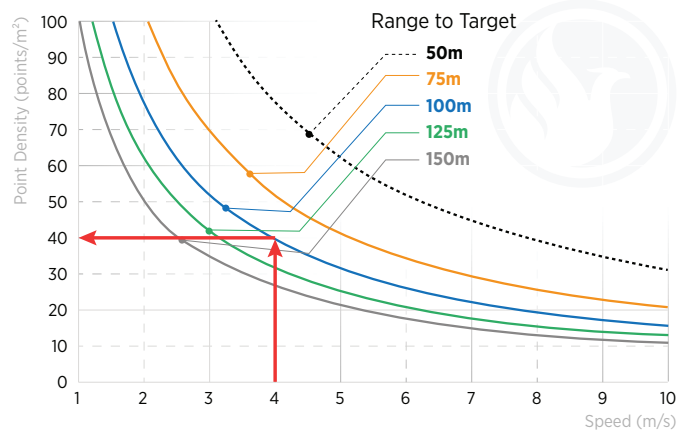
³⁾ Expected RMSEz when following the PLS recommended acquisition & processing workflow and ASPRS check point guidelines

MAX MEASUREMENT RANGE & POINT DENSITY miniRANGER-LITE



MTA 1
No ambiguity / one transmitted pulse "in the air"

— @ visibility 23km
— @ visibility 15km
— @ visibility 8km



EXAMPLE
miniRanger at 100k pulses/s
Range to target = 100 m, speed 4 m/s

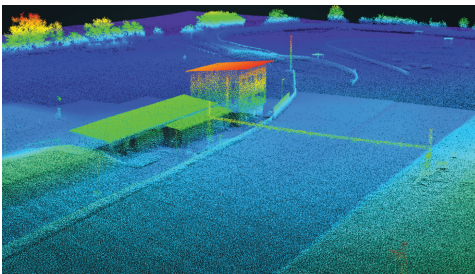
Resulting Point Density 40 pts/m²

The following conditions are assumed for the Operating Flight Altitude AGL

- ambiguity resolved by multiple-time-around (MTA) processing and flight planning
- target size ≥ laser footprint
- average ambient brightness
- operating flight altitude given at a FOV of +/-45°

Source: RIEGL Laser Measurement Systems.

miniRANGER-LITE SAMPLE DATA



PHOENIX SOFTWARE SUITE



Phoenix LiDAR Systems provides a proprietary complete software suite for streamlined mission planning, acquisition, georeferencing, data fusion, analysis & export.

Explore the effects that different parameters have on your data before you fly. Estimate your data quality and reduce costs by experimenting with various flight paths, altitudes, and other variables using the **Phoenix FlightPlanner**.

Streamline your LiDAR acquisition and post-processing with **SpatialExplorer**. Real-time point clouds and detailed navigation feedback enable in-field QA/QC to ensure operators and pilots have the feedback they need to collect the best data. This desktop software then gives you full control over each step of data processing. LiDARSnap and CameraSnap provide industry leading results for datasets from airborne, mobile, or other platforms. Analytic tools then transform your highly accurate data into actionable products and automatically generated quality reports.

SAVE TIME, GROW YOUR BUSINESS



Automated Post-Processing in the Cloud

Meet **LiDARMill**, the first cloud-based LiDAR post-processing platform that enables surveying teams to take advantage of precision laser mapping without investing in expensive post-processing software and training.

Processing your LiDAR data in the cloud has never been easier. View your data, track project status, and invite clients to view point clouds – all from your LiDARMill dashboard with faster turnaround times and lower overhead costs.

LiDARMill can be customized to serve any size organization, from small survey teams to government departments with heavy post-processing requirements. Contact sales@phoenixlidar.com for pricing and packages.

EXPLORE A PHOENIX LiDAR SYSTEM FOR YOUR TEAM, CONTACT US!

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