





QUICK SPECS

ABSOLUTE ACCURACY

2-3 cm RMSEz @ 100 $m^{(1)(2)(4)}$

INTRASWATH PRECISION

2 cm RMSDz @ 100 m⁽¹⁾⁽²⁾⁽³⁾

WEIGHT (including camera)

4.9 kg / 10.8 lbs

LASER RANGE

290 m @ 20% reflectivity, 200 kHz

SCAN RATE

500 kHz, up to 4 returns

APPLICATIONS



OIL & GAS SURVEYING



UTILITIES MAPPING



RAILWAY TRACK MAPPING



AGRICULTURE & FORESTRY MONITORING



CONSTRUCTION SITE SURVEYING

OPEN PIT MINING OPERATIONS



GENERAL MAPPING

1) Approximate values based on PLS test conditions.

2) Using a 90° downward field of view.

3) Range of elevation values on flat surfaces with >20% reflectivity at the laser's wavelength
4) Expected RMSEz when following the PLS recommended acquisition & processing workflow and ASPRS check point guidelines

PIONEER-360

The **PIONEER-360** is a best-in-class universal survey grade LiDAR mapping system. It is the tool of choice for UAV and Mobile applications where there is no room for compromise in data quality. With a beam divergence of only 0.3 mrad, this system is designed for precision and confidence. The **PIONEER-360** supports selectable pulse repetition rates up to 500 kHz and line scan speeds up to 250 lines/second, allowing it to be optimized for various application and data requirements. A quick release system can accommodate a removable high-resolution, light-weight 61 MP camera.

FEATURES

- Narrow beam divergence of 0.3 mrad for superior precision and canopy penetration
- Shot-to-shot precision of <1 cm for survey applications
- Scan speed of 250 lines per second for even x-y point distribution at higher vehicle speeds

PLATFORM

| OPERATING TEMPERATURE (MIN/MAX) | 0°/+40°C | | |
|---------------------------------|--------------------|--|--|
| STORAGE TEMPERATURE (MIN/MAX) | -20°/+50° C | | |
| DIMENSIONS w/o CAMERA | 348 x 170 x 150 mm | | |
| WEIGHT w/o CAMERA | 4.4 kg | | |
| OPERATING VOLTAGE | 12 - 28 VDC | | |
| POWER CONSUMPTION | 60 W (typical) | | |

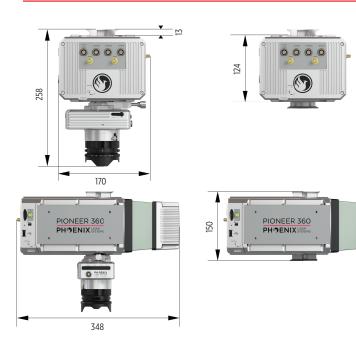
LIDAR SENSOR

| RANGE MEASUREMENT PRINCIPLE | Time of Flight | |
|-----------------------------------|--------------------------------------|--|
| MINIMUM RANGE | 1.5 m | |
| MAXIMUM RANGE | 290 m @ 20% reflectivity, 200 kHz | |
| PULSE REPETITION FREQUENCY | 200 kHz, 500 kHZ selectable | |
| BEAM DIVERGENCE (1/E2) | 0.3 mrad | |
| WAVE LENGTH | 1550 nm | |
| LASER SAFETY CLASSIFICATION | Class 1 | |
| LASER WEIGHT | 3.5 kg | |
| RANGE RESOLUTION | 2 mm | |
| INTENSITY RECORDING | 12 bits | |
| MAXIMUM NUMBER OF RETURNS | 4 (First, Second, Second Last, Last) | |
| RANGE ACCURACY 1 SIGMA | 10 mm | |
| PRECISION SINGLE SHOT | 5 mm | |
| FIELD OF VIEW | 360° | |
| LINES PER SECOND (SCAN FREQUENCY) | 50 – 250 lines/sec | |

NAVIGATION SYSTEM

| CONSTELLATION SUPPORT | GPS + GLONASS + BEIDOU + GALILEO | |
|--------------------------------|---|--|
| SUPPORT ALIGNMENT | Kinematic, Single-Antenna or optional Dual-Antenna | |
| OPERATION MODES | Real-time, Post processing optional | |
| ACCURACY POSITION | 1 cm + 1 ppm RMS horizontal | |
| IMU GYRO IN-RUN BIAS STABILITY | 1.0°/hr to 0.5°/hr options | |

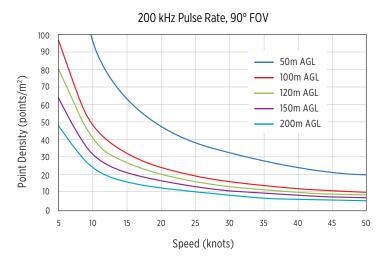
RANGE MEASUREMENT PERFORMANCE

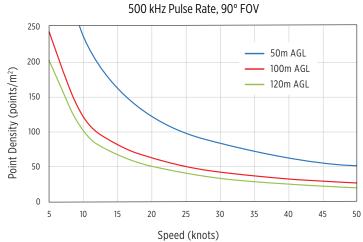


| Laser Pulse Repetition Frequency (PRF) | 200 kHz | 500 kHz | | |
|---|-------------------------|-------------------------|--|--|
| Maximum Measuring Range (1) | | | | |
| @ 10% target reflectivity @ 20% target reflectivity @ 50% target reflectivity | 205 m 290 m 490 m | 130 m 185 m 250 m | | |
| Typical Operating Flight (1) | | | | |
| @ 10% target reflectivity @ 20% target reflectivity @ 50% target reflectivity | 130 m 185 m 315 m | 85 m 120 m 160 m | | |

⁽¹⁾ Source Teledyne Optech Incorporated

SPEED VS. POINT DENSITY





PIONEER-360 ACCESSORIES



Wheel Sensor



Ground Vehicle Roof Rack Mount



360° Mobile Camera



61 MP Camera



EXPLORE A PHOENIX LIDAR SYSTEM FOR YOUR TEAM, CONTACT US!

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