















# **QUICK SPECS**

ABSOLUTE ACCURACY 25-50 mm @ 350 m range

PP ATTITUDE HEADING RMS ERROR 0.010° / 0.019° IMU options

WEIGHT (including AIR NavBox) 4.7 kg / 10.4 lbs

DIMENSIONS (with AIR NavBox) 348.5 x 164 x 189 mm

LASER RANGE 1200 m @ 20% reflectivity

SCAN RATE 1800 kHz, up to 15 returns

### **APPLICATIONS**

UTILITIES MAPPING





AGRICULTURE & FORESTRY MONITORING



GENERAL MAPPING



The **RANGER-XL** is a lightweight airborne laser scanner, especially designed for use on UAS and small manned airplanes or helicopters. With a wide field of view of 75 degrees and an extremely fast data acquisition rate of up to 1800 kHz, the **RANGER-XL** is perfectly suited for high point density corridor mapping applications such as power line, railway track and pipeline inspection.

# **FEATURES**

- Easily mountable to unmanned platforms (UAVs) and to helicopters, gyrocopters, and other small manned aircrafts.
- Operating flight altitude up to 1,400 m/4,600 ft
- Scan speed up to 400 lines/second

### PLATFORM

OVERALL DIMENSIONS (with AIR NavBox)	352 x 164 x 185 mm
OPERATING VOLTAGE	14 - 28 VDC
POWER CONSUMPTION	75 W
OPERATING TEMPERATURE	0° - +40° C
WEIGHT (including Air NavBox)	4.7 kg / 10.4 lbs

#### LIDAR SENSOR

LASER PROPERTIES	1550 nm
RANGE MIN	5 m
MAX EFFECTIVE MEASUREMENT RATE	up to 1,500,000 meas./sec
HORIZONTAL FIELD OF VIEW	75°
ACCURACY	20 mm
Precision	15 mm
LASER BEAM DIVERGENCE	0.35 mrad
LASER BEAM FOOTPRINT (Gaussian beam definition)	35 mm @ 100 m, 175 mm @ 500 m, 350 mm @ 1000 m
MAX MEASURING RANGE $ ho$ 20% ( $ ho$ 60%)	1200 m (1900 m)
SENSOR CLASSIFICATION	IP64 dust and splash-proof
WEIGHT	$\leq$ 3.8 kg (without IMU/GNSS)
POWER CONSUMPTION	65 W

### NAVIGATION SYSTEM

CONSTELLATION SUPPORT SUPPORTED ALIGNMENT **OPERATION MODES** ACCURACY POSITION ACCURACY ATTITUDE<sup>(5)</sup> ROLL, PITCH HEADING

GPS + GLONASS + BEIDOU + GALILEO Kinematic, Dual-Antenna Real-time, Post-Processed 1 cm + 1 ppm GNSS baseline RMS Horizontal

0.002° RMS 0.007° RMS

#### **RANGER-XL DIMENSIONS (mm)**



### RANGE MEASUREMENT PERFORMANCE

Laser Pulse Repetition Rate PRR $^{\mbox{\tiny D}}$	150 kHz	300 kHz	600 kHz	1200 kHz	1800 kHz
Max. Measuring Range <sup>2) 3)</sup>					
natural targets $P ≥ 20\%$	1200 m	850 m	650 m	450 m	350 m
natural targets $P ≥ 60\%$	1900 m	1400 m	1050 m	750 m	650 m
Max. Operating Flight Altitude AGL <sup>2) 4)</sup>	900 m	600 m	500 m	350 m	250 m
	(2950 ft)	(1950 ft)	(1650 ft)	(1150 ft)	(800 ft)
(a) $P \ge 20\%$	1400 m	1050 m	900 m	550 m	500 m
(b) $P \ge 60\%$	(4600 ft)	(3450 ft)	(2950 ft)	(1800 ft)	(1650 ft)
Max. Number of Targets per Pulse <sup>5)</sup>	15	15	15	8	5

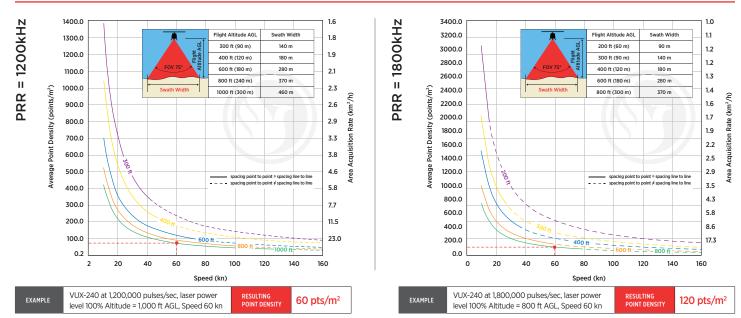
1) Rounded average PRR

2) Typical values for average conditions and average ambient brightness. In bright sunlight, the max. range is shorter than under an overcast sky.

3) The maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence, and for atmospheric visibility of 23 km. Range

ambiguities have to be resolved by multiple-time-around processing. 4) Effective FOV 75°, additional roll angle ± 5°.

5) If the laser beam hits, in part, more than one target, the laser's pulse power is split accordingly. Thus the achievable range is reduced.



# MAX MEASUREMENT RANGE & POINT DENSITY RANGER-XL

# **RANGER-XL ACCESSORIES**





EXPLORE A PHOENIX LIDAR SYSTEM FOR YOUR TEAM, CONTACT US! PhoenixLiDAR.com • sales@phoenixlidar.com • USA +1.323.577.3366